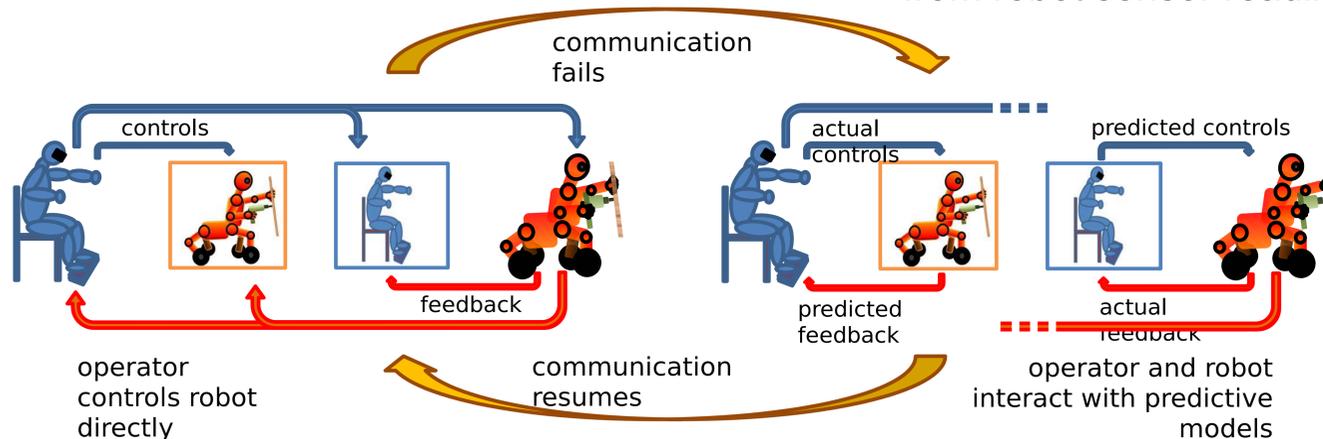


# CENTAURO

The CENTAURO concept comprises different modes of operation for the robot and the operators.

The main operator either directly controls the CENTAURO robot (left) ...

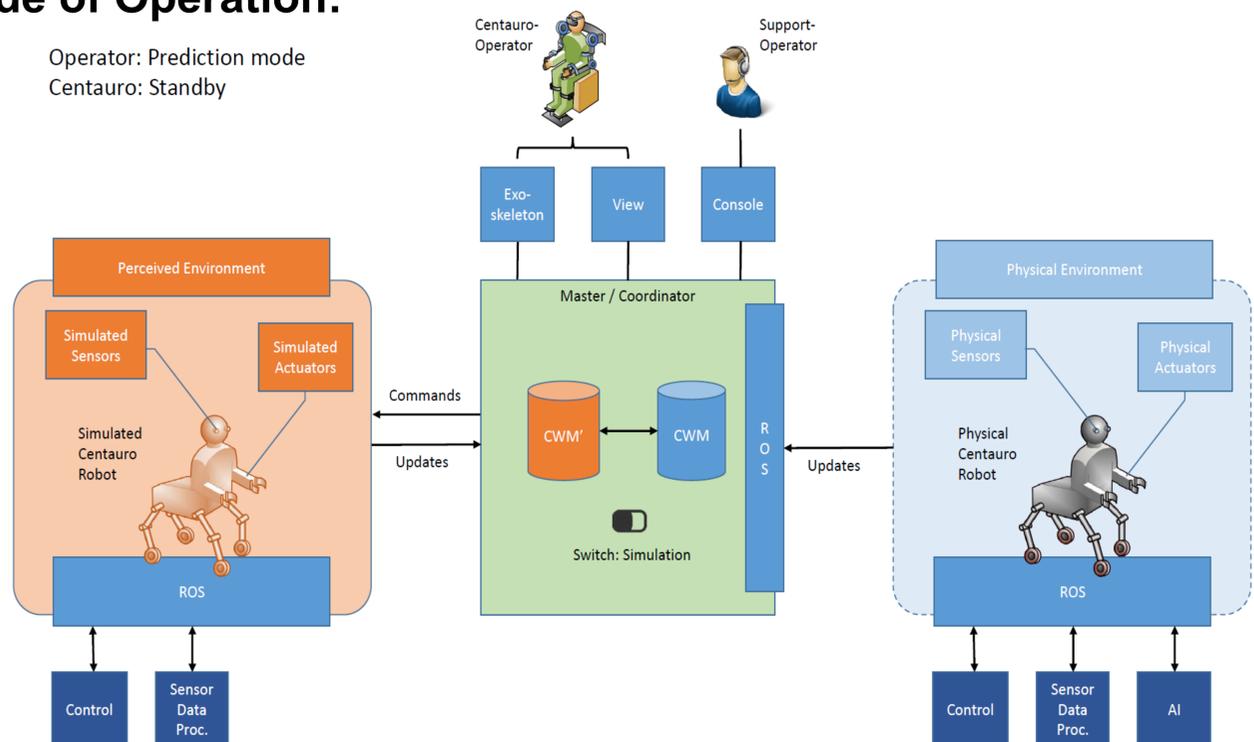
... or interacts with a predictive model of the robot and its environment, which has been instantiated from robot sensor readings (right).



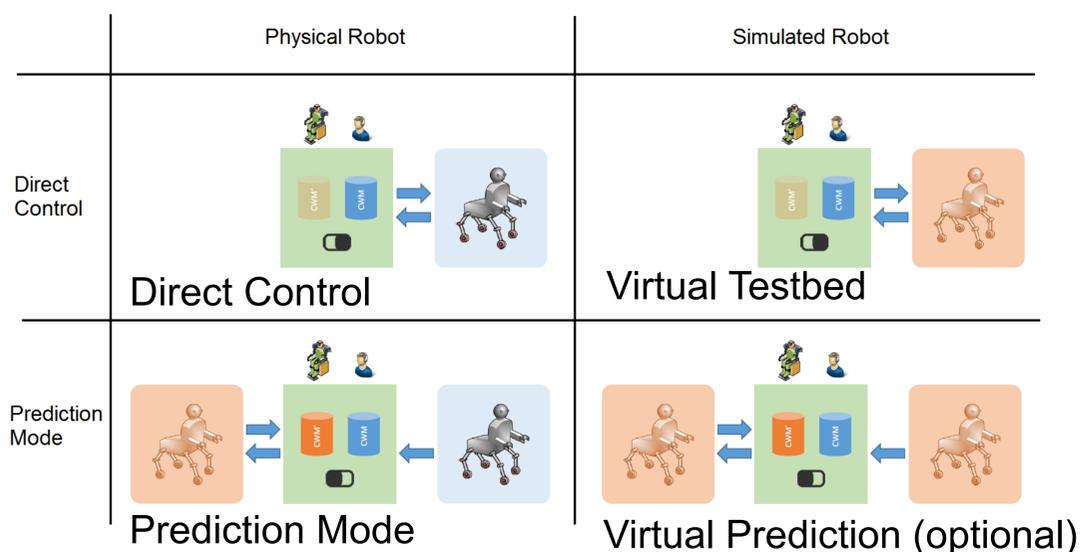
## Prediction Mode - Final Mode of Operation:

The Prediction Mode will be the final operation mode.

Operator: Prediction mode  
Centaur: Standby



## The four CENTAURO operation modes:



The four CENTAURO operation modes:

- Direct Control
- Virtual Testbed
- Prediction Mode - Final Operation
- Virtual Prediction (optional)